SOME MODIFICATIONS OF THE TRAPEZOIDAL RULE

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ABSTRACT. By using the quadratic interpolating spline a new class of the quadrature rules was obtained. Those formulas are modifications of the well known trapezoidal rule. The basic characteristic of those formulas is a free parameter. With appropriate choice of that parameter, accuracy of the trapezoidal rule can be improved up to $O(h^4)$. Besides this, by using this nonstandard techniques some well known quadrature rules were also obtained.

1. INTRODUCTION AND PRELIMINARIES

1.1. Classical quadrature rules. Classical quadrature rules are studied at basic courses in numerical analysis and they are here just used to provide an system of notation.

Let $a = x_0 < x_1 < \cdots < x_{2m} = b$, where $x_k = x_0 + kh$ and let $f_k = f(x_k), 0 \le k \le 2m$. Then

$$\int_{a}^{b} f(x)dx = Q_{R}[f, a, b, 2m] + E_{R}[f, a, b, 2m],$$

$$\int_{a}^{b} f(x)dx = Q_{R}[f, a, b, 2m] + E_{R}[f, a, b, 2m],$$

or

$$\int_{a}^{b} f(x)dx = Q_{S}[f, a, b, 2m] + E_{S}[f, a, b, 2m],$$

where

$$Q_R[f, a, b, 2m] = 2h \sum_{k=1}^m f_{2k-1}$$
(1)

is a generalized rule for the central rectangles, while

$$Q_S[f, a, b, n] = \frac{h}{3} \left(f_0 + 2 \sum_{k=1}^{m-1} f_{2k} + 4 \sum_{k=1}^m f_{2k-1} + f_{2m} \right)$$
(2)

is a generalized Simpsons rule. Errors of those formulas are respectively:

$$E_R[f, a, b, 2m] = \frac{(b-a)f''(\bar{\xi}_R)}{6}h^2,$$
(3)

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for some $\overline{\xi}_R \in [a, b]$, supposing $f \in C^2[a, b]$ and

$$E_S[f, a, b, 2m] = -\frac{(b-a)f^{iv}(\overline{\xi}_S)}{180}h^4,$$
(4)

for some $\overline{\xi}_S \in [a, b]$, supposing $f \in C^4[a, b]$. Furthermore, if $a = x_0 < x_1 < \cdots < x_n = b$, then

$$\int_{a}^{b} f(x)dx = Q_{T}[f, a, b, n] + E_{T}[f, a, b, n],$$

where

$$Q_T[f, a, b, n] = \frac{h}{2} \left(f_0 + 2 \sum_{k=1}^{n-1} f_k + f_n \right)$$

is the generalized trapezoidal rule and

.,

$$E_T[f, a, b, n] = -\frac{(b-a)f''(\xi_T)}{12}h^2$$

for some $\overline{\xi}_T \in [a, b]$, supposing $f \in C^2[a, b]$, is error for this rule.

1.2. Quadratic interpolating spline. Since that quadratic interpolating spline is usually avoided in the literature, basic details about it's construction are presented here (the cubic spline is most often considered, see [1, 3]).

Definition 1. Let $\Delta = \{a = x_0 < x_1 < \cdots < x_n = b\}$ be partition of the interval [a, b]. The function $S_{\Delta} : [a, b] \to \mathbb{R}$, with the following properties:

1. S_{Δ} is a polynomial of the second degree in every subinterval $[x_k, x_{k+1}], 0 \le k \le n-1$ and

2.
$$S_{\Delta} \in C^1[a, b]$$

is called the quadratic spline in relation to the partition Δ . If the interpolating properties

• $S_{\Delta}(x_k) = f(x_k), 0 \le k \le n$

are added to the previous definition, the quadratic interpolating spline of the function f will be obtained, usually denoted by $S_{\Delta,f}$.

Let the values $f_k = f(x_k), 0 \le k \le n$, of the function f, be given. From the property 1. of the Definition 1, it follows that

$$x \in [x_k, x_{k+1}] \Rightarrow S_{\Delta, f}(x) = a_k x^2 + b_k x + c_k = s_k(x), \ 0 \le k \le n-1,$$

which means that there are 3n unknown coefficients. To determine those coefficients 2n equations will be obtained from the interpolating properties, while n-1 equations will be obtained from property 2. of the same definition.

So, there is one parameter which can be chosen freely. The mentioned equations are:

$$a_k x_k^2 + b_k x_k + c_k = f_k, \ 0 \le k \le n - 1, \tag{5}$$

$$a_k x_{k+1}^2 + b_k x_{k+1} + c_k = f_{k+1}, \ 0 \le k \le n-1,$$
(6)

$$2a_k x_{k+1} + b_k = 2a_{k+1} x_{k+1} + b_{k+1}, \ 0 \le k \le n-2.$$

$$\tag{7}$$

After subtracting equation (5) from equation (6) we obtain:

$$b_k = \frac{f_{k+1} - f_k}{x_{k+1} - x_k} - a_k(x_{k+1} + x_k).$$

The last equation, together with equation (7), after elementary calculation gives the recurrence formulas for calculating the coefficients $a_k, 1 \le k \le n-1$. Hence, the coefficients of the quadratic interpolating spline can be calculated in the following way:

$$a_0$$
 – arbitrary,

$$a_{k+1} = \frac{f_{k+2} - f_{k+1}}{(x_{k+2} - x_{k+1})^2} - \frac{f_{k+1} - f_k}{(x_{k+2} - x_{k+1})(x_{k+1} - x_k)} - a_k \frac{x_{k+1} - x_k}{x_{k+2} - x_{k+1}}, \ 0 \le k \le n - 2,$$

$$b_k = \frac{f_{k+1} - f_k}{x_{k+1} - x_k} - a_k (x_{k+1} + x_k), \ 0 \le k \le n - 1,$$

$$c_k = f_k - a_k x_k^2 - b_k x_k, \ 0 \le k \le n - 1.$$
(8)

By using the formulas (8), again after elementary calculations, the basic modification of the trapezoidal rule will be obtained:

$$\int_{x_k}^{x_{k+1}} f(x)dx = \int_{x_k}^{x_{k+1}} s_k(x)dx + E[f, x_k, x_{k+1}]$$

= $(x_{k+1} - x_k) \left[\frac{1}{2} (f_{k+1} + f_k) - \frac{a_k}{6} (x_{k+1} - x_k)^2 \right] + E[f, x_k, x_{k+1}].$

If the partition of the interval [a, b] is uniform, i.e. if $x_k = x_0 + kh, 0 \le k \le n$, where $x_0 = a$ and $h = \frac{b-a}{n}$, then the first relation in (8) and the previous relation becomes much more simple:

$$a_{k} = \frac{f_{k+1} - 2f_{k} + f_{k-1}}{h^{2}} - a_{k-1}$$
$$= \sum_{i=1}^{k} (-1)^{k-i} \frac{f_{i+1} - 2f_{i} + f_{i-1}}{h^{2}} + (-1)^{k} a_{0}, \ 1 \le k \le n-1$$
(9)

and

$$\int_{x_k}^{x_{k+1}} f(x)dx = \frac{h}{2}(f_k + f_{k+1}) - \frac{h^3}{6}a_k + E[f, x_k, x_{k+1}], \ 0 \le k \le n-1.$$
(10)

Generalized formula (10) is

$$\int_{a}^{b} f(x)dx = Q_{T}[f, a, b, n] - \frac{h^{3}}{6} \sum_{k=0}^{n-1} a_{k} + E[f, a, b, n].$$
(11)

2. Basic results

2.1. The case n = 2m.

2.1.1. Simpsons rule. From the relations (9) and (11) it follows

$$\int_{a}^{b} f(x)dx = Q[f, a, b, 2m] + E[f, a, b, 2m],$$

where

$$Q[f, a, b, 2m] = \frac{h}{2} \left(f_0 + 2 \sum_{k=1}^{2m-1} f_k + f_{2m} \right) - \frac{h^3}{6} \sum_{k=0}^{2m-1} a_k$$
$$= \frac{h}{2} \left(f_0 + 2 \sum_{k=1}^{2m-1} f_k + f_{2m} \right)$$
$$- \frac{h^3}{6} \sum_{k=1}^{m} \frac{f_{2k} - 2f_{2k-1} + f_{2k-2}}{h^2}$$
$$= Q_S[f, a, b, 2m].$$
(12)

Now from (4) it follows that

$$E[f, a, b, 2m] = E_S[f, a, b, 2m] = -\frac{(b-a)f^{iv}(\xi_S)}{180}h^4,$$

for some $\overline{\xi}_S \in [a, b]$, assuming $f \in C^4[a, b]$.

2.1.2. The first modification. If the equation

$$\frac{f_{2k} - 2f_{2k-1} + f_{2k-2}}{h^2} = f_{2k-1}'' + \frac{f^{iv}(\tau_k)}{12}h^2,$$

(for some $\tau_k \in [x_{2k-2}, x_{2k}]$, assuming $f \in C^4[a, b]$) is put in (12), the first modification of the trapezoidal rule will be obtained

$$\int_{a}^{b} f(x)dx = Q_{1}[f, a, b, 2m] + E_{1}[f, a, b, 2m],$$

where

$$Q_1[f, a, b, 2m] = \frac{h}{2} \left(f_0 + 2 \sum_{k=1}^{2m-1} f_k + f_{2m} \right) - \frac{h^3}{6} \sum_{k=1}^{m} f_{2k-1}''$$
(13)

and

$$E_1[f, a, b, 2m] = -\frac{(b-a)f^{iv}(\overline{\xi}_S)}{180}h^4 - \frac{h^3}{6}\sum_{k=1}^m \frac{h^2}{12}f^{iv}(\tau_k)$$
$$= -\frac{(b-a)f^{iv}(\overline{\xi}_S)}{180}h^4 - \frac{(b-a)f^{iv}(\overline{\tau})}{144}h^4$$
$$= -\frac{(b-a)f^{iv}(\overline{\tau}_1)}{80}h^4,$$

for some $\overline{\tau}_1 \in [a, b]$.

2.1.3. The second modification. Formulas (1) and (3) together give:

$$f_{2m}' - f_0' = \int_{x_0}^{x_{2m}} f''(x) dx = 2h \sum_{k=1}^m f_{2k-1}'' + \frac{(b-a)f^{iv}(\overline{\xi}_R)}{6}h^2,$$

and from this relation follows the second modification of the trapezoidal rule (well known Ermits quadrature rule, for example see [2, 3]). Hence:

$$\int_{a}^{b} f(x)dx = Q_{2}[f, a, b, 2m] + E_{2}[f, a, b, 2m],$$

where

$$Q_2[f, a, b, 2m] = \frac{h}{2} \left(f_0 + 2 \sum_{k=1}^{2m-1} f_k + f_{2m} \right) - \frac{h^2}{12} (f'_{2m} - f'_0)$$
(14)

and

$$E_{2}[f, a, b, 2m] = \frac{(b-a)f^{iv}(\overline{\xi}_{R})}{72}h^{4} - \frac{(b-a)f^{iv}(\overline{\tau}_{1})}{80}h^{4}$$
$$= \frac{b-a}{720} \left(10f^{iv}(\overline{\xi}_{R}) - 9f^{iv}(\overline{\tau}_{1})\right)h^{4}, \tag{15}$$

for some $\overline{\xi}_R, \overline{\tau}_1 \in [a, b]$.

The estimation of the error (15) is much less exact then the estimation which can be found in [2], but these estimations becomes equal if we assume that $10f^{iv}(\overline{\xi}_R) - 9f^{iv}(\overline{\tau}_1) \in [m_4, M_4]$, where $m_4 = \min_{x \in [a,b]} f^{iv}(x)$ and $M_4 = \max_{x \in [a,b]} f^{iv}(x)$.

One can check that both of formulas (13) and (14) are exact for all polynomials of the third degree.

2.2. The case n = 2m + 1. Combining the formulas (2) and (10) gives

$$\int_{a}^{b} f(x)dx = \int_{x_{0}}^{x_{1}} f(x)dx + \int_{x_{1}}^{x_{2m+1}} f(x)dx$$
$$= Q_{T}[f, x_{0}, x_{1}] - \frac{h^{3}}{6}a_{0} + Q_{S}[f, x_{1}, b, 2m]$$
$$+ E[f, a, b, 2m + 1], \qquad (16)$$

where $Q_T[f, x_0, x_1] = \frac{h}{2}(f_0 + f_1)$, and parameter a_0 can be chosen arbitrarily. In general, accuracy of the previous rule is $O(h^3)$, but it can be improved up to $O(h^4)$ with an appropriate choice of the parameter a_0 . One of the possibilities is to choose the parameter a_0 to be equal to the main part of the reminder $E_T[f, x_0, x_1] = -\frac{f''(\xi_T)}{12}h^3, \xi_T \in [x_0, x_1].$

2.2.1. The first modification. For every $\lambda \in [0, 1]$, there exists (at least one) $X \in [x_0, x_1]$ such that $f''(X) = \lambda f''_0 + (1 - \lambda)f''_1$. Then

$$f''(\xi_T) = f''(X) + f'''(\theta)(\xi_T - X), \theta \in [\xi_T, X],$$

so that with the choice $a_0 = \frac{f''(X)}{2}$ we get:

$$\int_{a}^{b} f(x)dx = Q_{1}[f, a, b, 2m+1] + E_{1}[f, a, b, 2m+1],$$

where

$$Q_1[f, a, b, 2m+1] = \frac{h}{2}(f_0 + f_1) - \frac{h^3 f''(X)}{12} + Q_S[f, x_1, b, 2m]$$
(17)

and

$$E_1[f, a, b, 2m+1] = -\frac{f'''(\theta)}{12}(\xi_T - X)h^3 - \frac{(b-x_1)f^{iv}(\overline{\xi}_S)}{180}h^4,$$

for some $\xi_T, X \in [x_0, x_1], \theta \in [\xi_T, X], \overline{\xi}_S \in [x_1, b].$

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The combination of the formulas (13) and (17) gives

$$\int_{a}^{b} f(x)dx = \widetilde{Q}_{1}[f, a, b, 2m+1] + \widetilde{E}_{1}[f, a, b, 2m+1].$$

where

$$\widetilde{Q}_1[f, a, b, 2m+1] = \frac{h}{2} \left(f_0 + 2\sum_{k=1}^{2m} f_k + f_{2m+1} \right) - \frac{h^3}{6} \left(\frac{f''(X)}{2} + \sum_{k=1}^{m} f_{2k}'' \right)$$

and

$$\widetilde{E}_1[f, a, b, 2m+1] = -\frac{f'''(\theta)}{12}(\xi_T - X)h^3 - \frac{(b-x_1)f^{iv}(\overline{\tau}_1)}{80}h^4$$

for some $\xi_T, X \in [x_0, x_1], \theta \in [\xi_T, X], \overline{\tau}_1 \in [x_1, b].$

2.2.2. The second modification. Since we have

$$f''(\xi_T) = \frac{f'_1 - f'_0}{h} - \frac{(x_1 - \xi_T)^2 f'''(\theta_1) - (x_0 - \xi_T)^2 f'''(\theta_0)}{2h},$$

for some $\theta_0 \in [x_0, \xi_T], \theta_1 \in [\xi_T, x_1]$, the choice $a_0 = \frac{f_1' - f_0'}{2h}$ gives

$$\int_{a}^{b} f(x)dx = Q_{2}[f, a, b, 2m+1] + E_{2}[f, a, b, 2m+1],$$

where

$$Q_2[f, a, b, 2m+1] = \frac{h}{2}(f_0 + f_1) - \frac{h^2}{12}(f_1' - f_0') + Q_S[f, x_1, b, 2m]$$
(18)

and

$$E_2[f, a, b, 2m+1] = \frac{(x_1 - \xi_T)^2 f'''(\theta_1) - (x_0 - \xi_T)^2 f'''(\theta_0)}{24} h^2 - \frac{(b - x_1) f^{iv}(\overline{\xi}_S)}{180} h^4,$$

for some $\theta_0 \in [x_0, \xi_T], \theta_1 \in [\xi_T, x_1], \overline{\xi}_S \in [x_1, b]$. Similarly as in the previous case, the formulas (14) and (18) together give

$$\int_{a}^{b} f(x)dx = \widetilde{Q}_{2}[f, a, b, 2m+1] + \widetilde{E}_{2}[f, a, b, 2m+1],$$

where

$$\widetilde{Q}_2[f, a, b, 2m+1] = \frac{h}{2} \left(f_0 + 2\sum_{k=1}^{2m} f_k + f_{2m+1} \right) - \frac{h^3}{12} (f'_{2m+1} - f'_0)$$

(again Ermits quadrature rule) and

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$$\widetilde{E}_{2}[f, a, b, 2m+1] = \frac{(x_{1} - \xi_{T})^{2} f'''(\theta_{1}) - (x_{0} - \xi_{T})^{2} f'''(\theta_{0})}{24} h^{2} - \frac{(b - x_{1})h^{4}}{720} (10f^{iv}(\overline{\xi}_{R}) - 9f^{iv}(\overline{\tau}_{1})),$$

for some $\theta_0 \in [x_0, \xi_T], \theta_1 \in [\xi_T, x_1], \overline{\xi}_R, \overline{\tau}_1 \in [x_1, b].$

2.3. Another possibility for the choice of the parameter a_0 . One can check that the parameter a_0 can not be chosen in a such way that formula (16) (without the last term) integrates exactly all polynomials with degree not greater than three. But, if $P(x) = Ax^3 + Bx^2 + Cx + D$, with the choice

$$a_0 = B + 3A(x_0 + \frac{h}{2}), \tag{19}$$

the formula (16) will be true for the polynomial P.

Furthermore, for every $X \in [x_0, x_1]$ one has

$$f(x) \approx f(X) + f'(X)(x - X) + \frac{1}{2}f''(X)(x - X)^2 + \frac{1}{6}f'''(X)(x - X)^3,$$

and in accordance with (19), with the choice

$$a_0 = \frac{1}{2} [f''(X) + f'''(X)(x_0 + \frac{h}{2} - X)],$$

the formula (16) (again without the last term) becomes exact for the "main part" of the function f. Hence,

$$\int_{a}^{b} f(x)dx = \overline{Q}_{2}[f, a, b, 2m+1] + \overline{E}_{2}[f, a, b, 2m+1].$$

In the last formula one has

$$\overline{Q}_{2}[f, a, b, 2m+1] = Q_{T}[f, x_{0}, x_{1}] - \frac{h^{3}}{12}[f''(X) + f'''(X)(x_{0} + \frac{h}{2} - X)] + Q_{S}[f, x_{1}, b, 2m],$$

while the order of accuracy is still $O(h^4)$, since

$$f''(\xi_T) = f''(X) + f'''(X)(\xi_T - X) + \frac{1}{2}f^{iv}(\theta)(\xi_T - X)^2,$$

and finally

$$\overline{E}_2 = -\frac{(\xi_T - x_0 - \frac{h}{2})f'''(X) + \frac{1}{2}(\xi_T - X)^2 f^{iv}(\theta)}{12}h^3 - \frac{(b - x_1)f^{iv}(\overline{\xi}_S)}{180}h^4.$$

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